

ABSTRACT OF THE DISCLOSURE

A method for controlling the driving dynamics of a vehicle provides that a steering movement is carried out on the basis of a set value, which is calculated as a function of a deviation between a desired value and an acquired actual value of a vehicle state variable.

In this method, at least one membership degree of an acquired value of a steering angle, which is set by a driver, and/or of a steering angle gradient, which is set by the driver, in a predetermined fuzzy set, are/is determined, and a value of the set value is changed as a function of the membership degree.